



# Vulkan SC

Mukund Keshava, System Software Engineer

Sruthik P, System Software Engineer





# Agenda

- Introduction to Vulkan

---
- Why Vulkan SC

---
- Basic Philosophy

---
- Vulkan SC vs Vulkan

---
- Vulkan SC Workflow

---
- Code examples



The background of the slide is a black field filled with abstract, glowing green lines and shapes. These elements resemble motion-blurred light trails or digital data paths. Some lines are straight and parallel, while others curve into loops or form complex, interconnected patterns. The green has a slight gradient, appearing brighter in some areas and more translucent in others, giving it a three-dimensional, ethereal quality.

# Introduction to Vulkan

# Graphics APIs before Vulkan – Fixed Function Era



1983

**SGI releases IRIS GL**

One of the first proprietary Graphics API



1996

**Microsoft releases DirectX 2**

Lower-level Graphics API targeting Windows OS

- Different approach compared to OpenGL
- Exposed two types of APIs: Immediate and Retained mode
- Uses concept of "execute buffers"

1993

**SGI releases OpenGL**



- Open-source variant of IRIS GL.
- OpenGL API designed around configuring a monolithic state machine.
- Low-level GPU hardware mechanisms abstracted away from API.
- Large driver overhead

1997 - 2000

**DirectX 3 - 7**

Execute buffers not preferred by developers and IHVs.

- Later versions of DirectX move to OpenGL style Draw APIs and drop execute buffers.
- Retained Mode API is dropped in favor of Immediate Mode.

# Graphics APIs before Vulkan – Programmable Era

2000

## DirectX 8

One of the first Graphics APIs to support "programmable" Vertex and Fragment Shaders

2004

## GLSL with OpenGL 2.0

- Open-source Shading language

2002

## HLSL with DirectX 9

- One of the first High Level Shading languages. GPUs start becoming more programmable.

2005 - 2012

## DirectX 10, 11 and GL 3,4

GPUs start becoming more programmable.

- More shader stages introduced (Tessellation, compute etc.)
- APIs are still relatively high level compared to consoles.
- GPGPU

# Graphics APIs before Vulkan – Programmable Era (Low Level APIs)



2016

**Khronos releases Vulkan 1.0**

- Open-source, platform agnostic low level Graphics API.

2015

**DirectX12**

- Microsoft's low level Graphics API.
- Supported only on Windows OS.



# Introduction

## Vulkan

- New API from Khronos, introduced in 2016.
- Low level
- Cross platform – Desktop & Mobile
- Deterministic
- Low driver overhead
- Multi-threading
- Ray Tracing
- Current version: 1.3



# Introduction

Comparison with OpenGL

## OpenGL

Implicit

Large driver  
overhead

Internal  
memory  
management

Object model  
prevents efficient  
multi-threading

Fewer lines of  
code

WSI not part  
of  
specification

## Vulkan

Explicit

Lesser driver  
overhead

Memory  
manged by app

Efficient multi-  
threaded support

More lines of  
code

WSI part of  
specification



# Introduction

## Concepts

### Pipeline

- Various pipelines supported – Graphics, Compute, RT.
- Shader modules to be provided. SPIR-V

### Memory

- All allocation done by application. Images, buffers need to be allocated and managed by app.

### Framebuffer

- Buffers into which the device renders into

### RenderPass

- Render Description

# Introduction

## Concepts

### Command Buffer

- Memory for recording device commands. Also needs to be allocated by the application.

### Synchronization

- Explicitly done by the application via various synchronization primitives.

### Swapchain

- Various backends present. Number of images specified by application.

### Descriptors

- Describe Shader Resources

# Introduction

Vulkan Design

## Application Flow

### Initial setup

Instance, Object creation

### Create/Allocate objects

Buffers (vertex, index etc.), Images, Command buffers, Sync objects

### Record commands

Command buffer recording

### Submit commands

Submit command buffers to queue



# Introduction

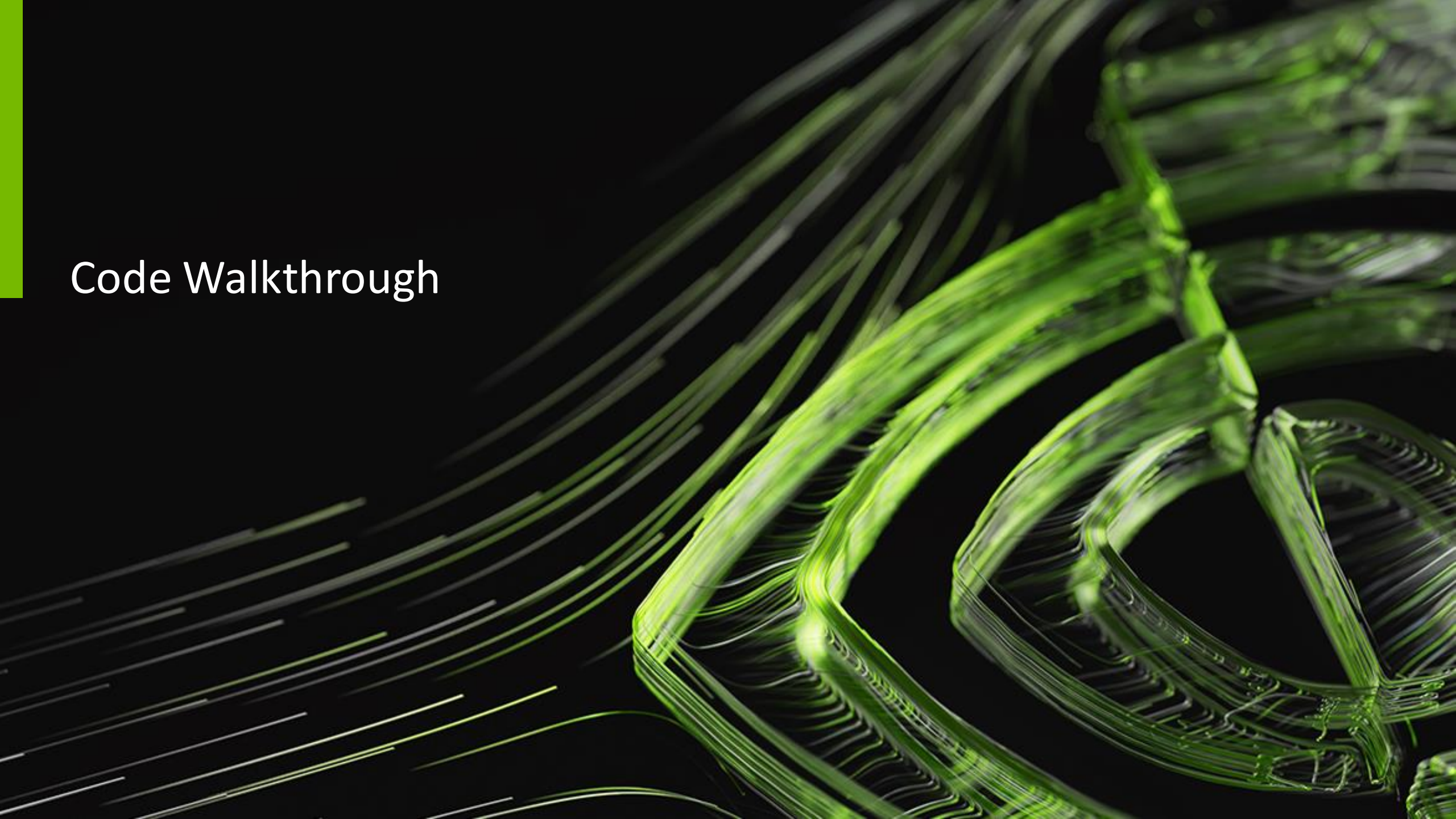
## Basics

- Vulkan uses structures to feed information to the driver.
- There are “info” structures that need to be filled. Example:

```
VkMemoryAllocateInfo allocInfo{};
allocInfo.sType          = VK_STRUCTURE_TYPE_MEMORY_ALLOCATE_INFO;
allocInfo.allocationSize = size;
allocInfo.memoryTypeIndex = findMemoryType(memRequirements.memoryTypeBits, properties);

vkAllocateMemory(device, &allocInfo, nullptr, &bufferMemory);
```

# Code Walkthrough





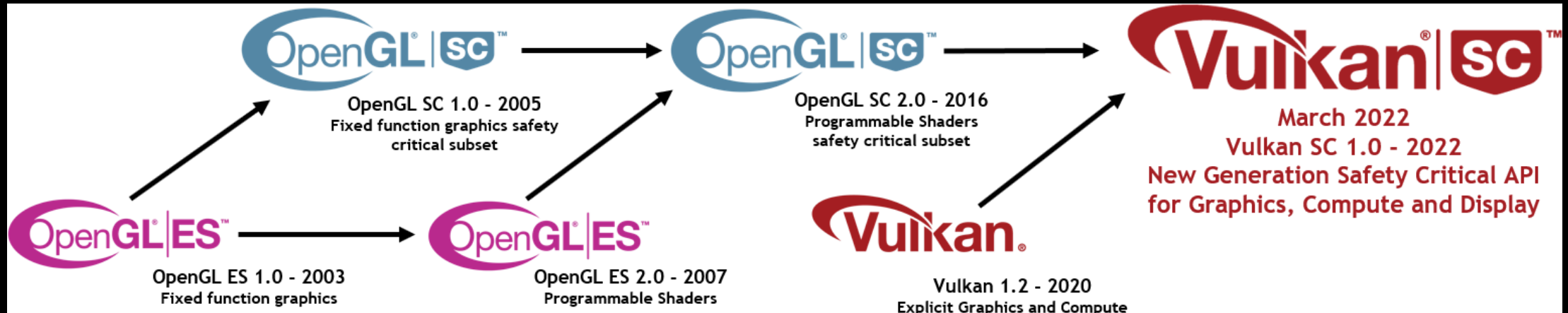
The background of the slide is a black field filled with abstract, glowing green elements. On the left, there are numerous thin, parallel lines of varying lengths, some slightly curved, creating a sense of motion or data flow. On the right side, there are more complex, thicker green structures that resemble stylized, overlapping leaf-like shapes or perhaps a network of interconnected paths. These shapes have a textured, almost crystalline appearance with internal details visible. The overall aesthetic is high-tech and futuristic.

# Why Vulkan SC



# Why Vulkan SC?

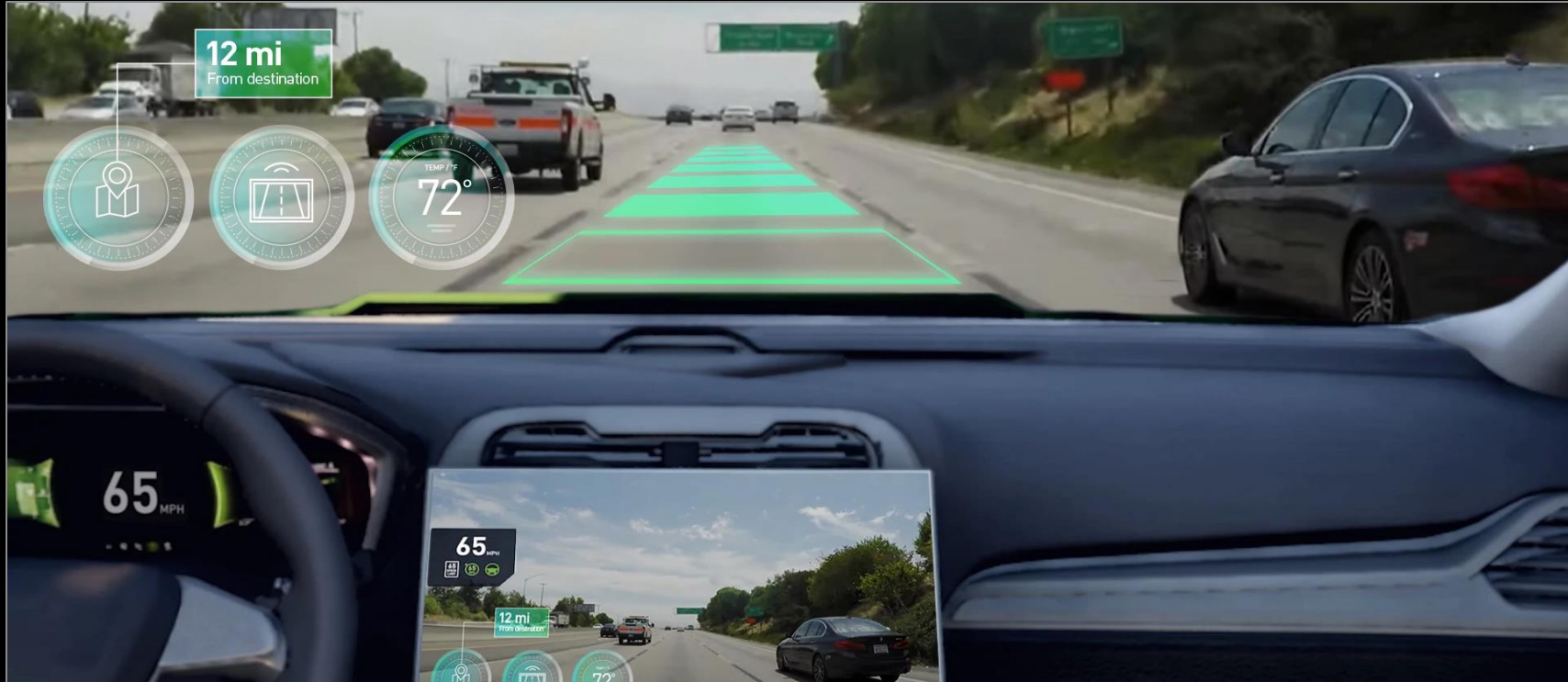
- Graphics is playing a larger role in safety critical industries like Automotive and Avionics.
- OpenGL-SC 2.0 (based on GLES 2.0) was the last safety-critical graphics API. Demands for next generation safety-critical Graphics continues to grow.
- The design of Vulkan SC gives safety-critical application developers detailed control of GPU acceleration in a way that can be rigorously specified and tested to meet safety certification standards such as RTCA [DO-178C](#) Level A / EASA ED-12C Level A (avionics); [IEC 61508](#) (industrial), [IEC 62304](#) (Medical), and [ISO 26262](#) ASIL D (automotive).



## Khronos Safety-Critical GPU API Evolution

Source: <https://www.khronos.org/VulkanSC/>

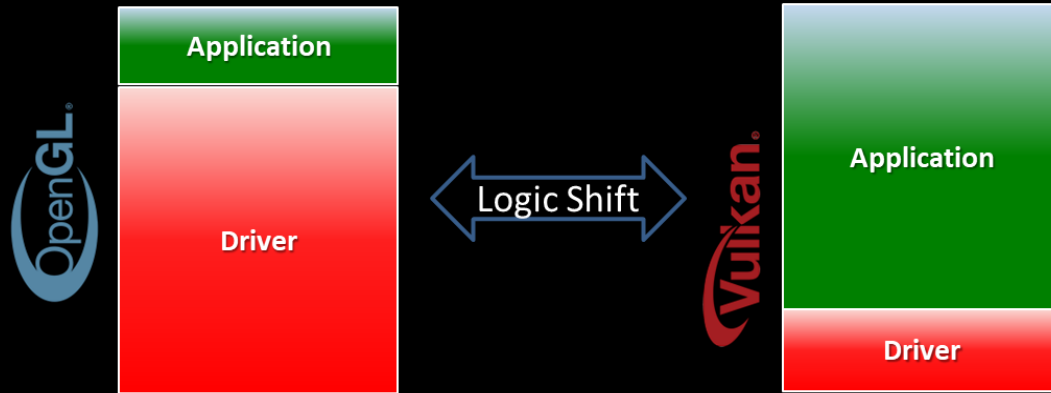
# Why Vulkan SC?



Vulkan SC simplifies the Safety certification process enabling manufacturers to deploy advanced graphics capabilities in ADAS systems.

<https://developer.nvidia.com/blog/using-vulkan-sc-for-safety-critical-graphics-and-real-time-gpu-processing/>

# Why Vulkan SC?



- Vulkan 1.2 API provides explicit control to applications over GPU work scheduling, synchronization and resource management.
- Minimal state tracking required in Vulkan implementations compared to GLES
- Using the low level Vulkan API as a starting point for Vulkan SC makes sense from a Safety certification point of view (Less code for IHVs to safety certify).
- Reduced driver complexity.



The background features a solid green vertical bar on the left. The rest of the image is a dark field filled with numerous thin, bright green lines that appear to be moving or vibrating, creating a sense of dynamic energy. Some lines are straight, while others are curved or bundled together.

# Basic Philosophy

# Philosophy

## Overview

### Deterministic Execution

- Predictable execution times and results for operations performed through Vulkan SC APIs

### Robustness

- Enhanced fault handling, removed ambiguity.

### Simplification

- Remove non-essential features to reduce Certification efforts.

# Philosophy

## Deterministic Execution

### Removal of Online compilation

- Online/Runtime compilation is not deterministic. Vulkan SC removes online/runtime compilation.
- Side-effect being the reduction of efforts for IHVs/System Integrators on safety certification

### Support for Offline compilation

- In lieu of online compilation, offline compilation support is introduced in Vulkan SC. Pre-compiled binaries are provided as input at runtime by the Vulkan SC application to the implementation. (More on this later).



# Philosophy

## Deterministic Execution

- Static Memory Allocation
  - Runtime memory allocation results in non-deterministic behavior via potential heap fragmentations, memory allocation errors etc.
  - Application specifies to Vulkan SC implementation/driver the upper bound for number and size of objects of all types that will exist. Implementation allocates memory based on this upper bound during “init” time and Object creation at runtime by application uses the pre-allocated memory.

# Philosophy

## Robustness

### Fault Handling and Reporting

- Application registers functions at device creation which the driver can call if a fault is detected.

### Vulkan SC Conformance Test Suite (CTS)

- Leverages existing Vulkan CTS with SC-specific test additions and can be used by IHVs / System integrators to confirm Vulkan SC implementation compatibility.

### MISRA C Headers

- Vulkan SC headers are aligned for compliance with MISRA C:2012 (A Software development guideline developed by the MISRA consortium for embedded system code safety, security, portability and reliability and alignment with safety-critical standards).

# Philosophy

## Simplification

Depth-stencil  
resolve made  
optional

Shader atomics  
made optional

Multiview made  
optional

Timeline  
semaphores made  
optional

Removal of sparse  
memory resources  
and sparse memory  
binding support

Removal of pipeline  
derivatives

Removal of host  
allocation callbacks

# Vulkan SC vs Vulkan



# Vulkan SC vs Vulkan

---

- Setup
- Offline Pipelines
- Commands
- Fault Handling
- Object Refresh



# Vulkan SC vs Vulkan

---

- Setup
- Offline Pipelines
- Commands
- Fault Handling
- Object Refresh

# Setup

## Instance

- Different API version is needed to create a Vulkan SC instance.
- Application info needs to be set differently, as shown below

```
VkApplicationInfo appInfo{};
appInfo.sType      = VK_STRUCTURE_TYPE_APPLICATION_INFO;
appInfo.pNext      = nullptr;
appInfo.pApplicationName = "hello_vksc";
appInfo.applicationVersion = 0;
appInfo.pEngineName   = nullptr;
appInfo.engineVersion  = 0;
appInfo.apiVersion     = VK_MAKE_API_VERSION(VKSC_API_VARIANT, 1, 0, 0);
```

# Setup

## Features & Properties

Vulkan SC supports similar features as Vulkan 1.2.

Exceptions are shader atomic instructions, multiview, depth-stencil resolve, etc. all of which are made optional.

The removals were made in order to reduce driver complexity and verification burden

Vulkan SC-specific device features and properties can be determined via `VkPhysicalDeviceVulkan SC10Features` and `VkPhysicalDeviceVulkan SC10Properties`

Vulkan SC adds a new memory heap type - `VK_MEMORY_HEAP_SEU_SAFE_BIT`

# Setup

## Device

Applications need to provide information to the driver upfront.

Vulkan SC introduces `VkDeviceObjectReservationCreateInfo`

Structure is chained to the `deviceInfo` for device creation.

# Setup

## Device

- Vulkan SC applications need to provide information to the driver up-front, to do all allocations.
- In order to support this, Vulkan SC introduces `VkDeviceObjectReservationCreateInfo`

```
VkDeviceObjectReservationCreateInfo devObjectResCreateInfo{};
devObjectResCreateInfo.sType = VK_STRUCTURE_TYPE_DEVICE_OBJECT_RESERVATION_CREATE_INFO;
devObjectResCreateInfo.pNext = nullptr;
devObjectResCreateInfo.pipelineCacheCreateInfoCount = pipelineCacheCreateInfoCount;
devObjectResCreateInfo.pPipelineCacheCreateInfos = pPipelineCacheCreateInfos;
devObjectResCreateInfo.pipelinePoolSizeCount = 0;
devObjectResCreateInfo.pPipelinePoolSizes = 0;
devObjectResCreateInfo.layeredImageViewRequestCount = 0;
devObjectResCreateInfo.pipelineCacheRequestCount = 1;
devObjectResCreateInfo.pipelineLayoutRequestCount = 1;
devObjectResCreateInfo.renderPassRequestCount = 1;
devObjectResCreateInfo.graphicsPipelineRequestCount = 1;
devObjectResCreateInfo.computePipelineRequestCount = 0;
devObjectResCreateInfo.descriptorSetLayoutRequestCount = 0;
devObjectResCreateInfo.samplerRequestCount = 0;
// . . .

// Create device
deviceInfo.pNext = &devObjectResCreateInfo;
err = vkCreateDevice(physdevs[0], &deviceInfo, NULL, &dev);
```



# Setup

## Objects

The `VkDeviceObjectReservationCreateInfo` structure provides upper bounds on maximum object count.

Objects can be created and destroyed, provided the maximum counts are taken into account.

The Vulkan SC implementation will perform its own host memory allocations. Support for application-provided memory allocation, as supported in base Vulkan, has been removed in Vulkan SC.

# Vulkan SC vs Vulkan

---

- Setup
- **Offline Pipelines**
- Commands
- Fault Handling
- Object Refresh

# Setup

## Pipeline Compilation

More deterministic compared to online compilation.

Reduced safety certification burden for implementations.

Online shader compilation not supported. Pipeline state needs to be represented offline.

`vkCreateShaderModule` removed from the API.

JSON as the format for offline pipeline representation. [Schema](#)

# Offline Pipelines

## JSON representation

- JSON as the format for offline pipeline representation. [Schema](#)
- Example portion of json shown below.

```
"GraphicsPipelineState" :
{
  "Renderpass" :
  {
    "sType" : "VK_STRUCTURE_TYPE_RENDER_PASS_CREATE_INFO",
    "pNext": "NULL",
    "flags" : "0",
    "attachmentCount" : 2,
    "pAttachments":
    [
      {
        "flags" : "0",
        "format" : "VK_FORMAT_B8G8R8A8_UNORM",
        "samples" : "VK_SAMPLE_COUNT_1_BIT",
        "loadOp" : "VK_ATTACHMENT_LOAD_OP_CLEAR",
        "storeOp" : "VK_ATTACHMENT_STORE_OP_STORE",
        "stencilLoadOp" : "VK_ATTACHMENT_LOAD_OP_DONT_CARE",
        "stencilStoreOp" : "VK_ATTACHMENT_STORE_OP_DONT_CARE",
        "initialLayout" : "VK_IMAGE_LAYOUT_UNDEFINED",
        "finalLayout" : "VK_IMAGE_LAYOUT_PRESENT_SRC_KHR"
      },
      {
        "flags" : "0",
        "format" : "VK_FORMAT_D32_SFLOAT_S8_UINT",
        "samples" : "VK_SAMPLE_COUNT_1_BIT",
        "loadOp" : "VK_ATTACHMENT_LOAD_OP_CLEAR",
        "storeOp" : "VK_ATTACHMENT_STORE_OP_STORE",
        "stencilLoadOp" : "VK_ATTACHMENT_LOAD_OP_CLEAR",
        "stencilStoreOp" : "VK_ATTACHMENT_STORE_OP_DONT_CARE",
        "initialLayout" : "VK_IMAGE_LAYOUT_UNDEFINED",
        "finalLayout" : "VK_IMAGE_LAYOUT_DEPTH_STENCIL_ATTACHMENT_OPTIMAL"
      }
    ]
  }
}
```



# Offline Pipelines

## Pipeline Compilation

Pipeline Cache Compiler is used to obtain pipeline cache.

Pipelines are identified at runtime via Pipeline Identifiers specified in `VkPipelineOfflineCreateInfo`

Pipeline Cache Utility can be used to extract information from cache.

Pipeline derivatives are not supported in Vulkan SC due to the use of read-only offline generated pipeline caches.

# Offline Pipelines

PCC

PCC creates offline cache that will be loaded by the runtime application.

PCC takes the SPIR-V shader modules and the JSON state as input and generates pipeline cache.

Necessary to create pipelines offline.

Generates vendor specific offline cache.

# Offline Pipelines

## Pipeline Pools

Memory for pipelines needs to be specified up-front.

Size provided in `VkDeviceObjectReservationCreateInfo` struct.

When a pipeline is destroyed, the memory becomes available for re-use if `recyclePipelineMemory` is supported.

[Pipeline Cache Utility](#) can be used to query pipeline size requirements.

Developer needs to obtain the pool size information offline.

# Offline Pipelines

## Pipeline Creation

In Vulkan SC, pipeline caches are mandated.

The application has to load the cache, specify all required information.

Pipeline state must match the state that was provided to PCC.

`VK_PIPELINE_CACHE_CREATE_READ_ONLY_BIT` specifies that the cache is read-only.

`VK_PIPELINE_CACHE_CREATE_USE_APPLICATION_STORAGE_BIT` specifies that the application will maintain the contents of the memory,



```
typedef struct VkPipelinePropertiesIdentifierEXT {  
    VkStructureType    sType;  
    void*              pNext;  
    uint8_t            pipelineIdentifier[VK_UUID_SIZE];  
} VkPipelinePropertiesIdentifierEXT;
```

```
VkPipelineOfflineCreateInfo pipelineOfflineCreateInfo{};  
pipelineOfflineCreateInfo.sType = VK_STRUCTURE_TYPE_PIPELINE_OFFLINE_CREATE_INFO;  
memcpy(pipelineOfflineCreateInfo.pipelineIdentifier, identifier, VK_UUID_SIZE);  
pipelineOfflineCreateInfo.poolEntrySize = PIPELINE_SIZE;
```

```
// Set it to the pipeline's pNext  
pipelineCreateInfo.pNext = &pipelineOfflineCreateInfo;
```

# Offline Pipelines

## Pipeline Creation

- `VkPipelineOfflineCreateInfo` set as pNext to `vkCreate*Pipelines()`
- UUID obtained via the JSON.

# Vulkan SC vs Vulkan

---

- Setup
- Offline Pipelines
- **Commands**
- Fault Handling
- Object Refresh

# Commands

## Command Pools

- Memory for command pools and buffers need to be allocated by the driver at “init” time.
- `VkCommandPoolMemoryReservationCreateInfo` needs to be provided by the application.
- `commandPoolReservedSize` is the number of bytes to be allocated for all command buffer data recorded into this pool.
- `commandPoolMaxCommandBuffers` is the maximum number of command buffers that can be allocated from this command pool.

```
typedef struct VkCommandPoolMemoryReservationCreateInfo {  
    VkStructureType    sType;  
    const void*        pNext;  
    VkDeviceSize        commandPoolReservedSize;  
    uint32_t            commandPoolMaxCommandBuffers;  
} VkCommandPoolMemoryReservationCreateInfo;
```

# Commands

## Command Pools

- Applications are expected to estimate their worst-case command buffer memory usage at development time using `vkGetCommandPoolMemoryConsumption` and reserve large enough command buffers
- **commandPoolAllocated** is the number of bytes currently allocated from this pool for command buffer data.
- **commandPoolReservedSize** is the total number of bytes available for all command buffer data recorded into this pool.
- **commandBufferAllocated** is the number of bytes currently allocated from this pool for the specified command buffer's data.

```
void vkGetCommandPoolMemoryConsumption(
    VkDevice          device,
    VkCommandPool     commandPool,
    VkCommandBuffer    commandBuffer,
    VkCommandPoolMemoryConsumption* pConsumption);

typedef struct VkCommandPoolMemoryConsumption {
    VkStructureType    sType;
    void*              pNext;
    VkDeviceSize       commandPoolAllocated;
    VkDeviceSize       commandPoolReservedSize;
    VkDeviceSize       commandBufferAllocated;
} VkCommandPoolMemoryConsumption;
```

# Commands

## Command Buffers

Each command recorded into a command buffer has an implementation-dependent size : `commandPoolReservedSize`.

Command buffers can be allocated and freed in a pool as needed.

Once command buffers are freed, they can once again be allocated from the command pool.

When a command pool is reset, the resources from all command buffers allocated from the command pool are returned back to the command pool.



# Vulkan SC vs Vulkan

---

- Setup
- Offline Pipelines
- Commands
- **Fault Handling**
- Object Refresh

# Fault Handling

## Safety Context

- Handling of failures is essential in safety critical contexts.
- In addition to the already existing VkResult enums returned by Vulkan APIs, Vulkan SC adds the following features for enhanced fault event communication between implementations and applications:
  - Optional checks against VUIDs being performed in Vulkan SC implementations.
    - Vulkan SC implementations can return a new VkResult enum “VK\_ERROR\_VALIDATION\_FAILED” to signify validation failures
  - Support for implementations invoking callbacks registered by applications when faults are detected
  - Support for applications querying current faults on demand.
- Performance-critical Vulkan APIs do not usually have error return codes. Vulkan SC implementations can optionally use the Fault Handling features of Vulkan SC to specify runtime faults occurring as part of these APIs.

```
typedef struct VkFaultCallbackInfo {
    VkStructureType      sType;
    void*                pNext;
    uint32_t             faultCount;
    VkFaultData*         pFaults;
    PFN_vkFaultCallbackFunction pfnFaultCallback;
} VkFaultCallbackInfo;
```

```
typedef void (VKAPI_PTR *PFN_vkFaultCallbackFunction)(
    VkBool32      unrecordedFaults,
    uint32_t      faultCount,
    const VkFaultData* pFaults);
```

```
VkFaultCallbackInfo faultCallbackInfo {};
faultCallbackInfo.sType = VK_STRUCTURE_TYPE_FAULT_CALLBACK_INFO;
faultCallbackInfo.pfnFaultCallback = FaultHandlerCallbackFn(); // Callback function
```

```
VkDeviceCreateInfo deviceCreateInfo {};
...
// Set it to the VkDeviceCreateInfo's pNext
deviceCreateInfo.pNext = &faultCallbackInfo;
```

```
// A fault is described as a VkFaultData struct
typedef struct VkFaultData {
    VkStructureType      sType;
    void*                pNext;
    VkFaultLevel         faultLevel;
    VkFaultType          faultType;
} VkFaultData;
```

# Fault Handling

## Fault handling call-backs

- A new struct `VkFaultCallbackInfo` specifying a function pointer to be invoked by the implementation when faults occur can be specified during `VkDevice` creation via extending `VkDeviceCreateInfo`.

```

VkResult vkGetFaultData(
    VkDevice          device,
    VkFaultQueryBehaviour faultQueryBehaviour,
    VkBool32*         pUnrecordedFaults,
    uint32_t*         pFaultCount,
    VkFaultData*       pFaults
);

// VkPhysicalDeviceVulkan SC10Properties.maxQueryFaultCount specifies
// the maximum number of faults that can be reported by the implementation.
VkFaultData faultData[VkPhysicalDeviceVulkan SC10Properties.maxQueryFaultCount];

// Get the current number of faults available.
VkBool32 unrecordedFaults;
uint32_t faultCount;
VkResult result;
VkFaultQueryBehaviour queryBehaviour = VK_FAULT_QUERY_BEHAVIOUR_GET_AND_CLEAR_ALL_FAULTS;
result = vkGetFaultData(device, queryBehaviour, &unrecordedFaults, &faultCount, nullptr);

// Get the fault data.
result = vkGetFaultData(device, queryBehaviour, &unrecordedFaults, &faultCount, faultData);

```

# Fault Handling

## Querying Fault Status

- In addition to fault handling call-backs, the number of current faults and fault data can be queried at runtime via the API `vkGetFaultData`.

# Vulkan SC vs Vulkan

---

- Setup
- Offline Pipelines
- Commands
- Fault Handling
- Object Refresh



# Object Refresh

VK\_KHR\_object\_refresh

Single Event Upset is any inadvertent state change that could cause flipping of bits.

[https://en.wikipedia.org/wiki/Single-event\\_upset](https://en.wikipedia.org/wiki/Single-event_upset)

Some Safety Critical applications may require this to be supported.

Host memory typically has error correction enabled for this.

Device memory may not be SEU safe.

Explicitly allocated buffer/images can be reloaded by the application.

# Object Refresh

VK\_KHR\_object\_refresh

There could be memory that's allocated by the driver without an explicit allocation by the application.

This memory is not addressable by the Vulkan SC app.

VK\_KHR\_object\_refresh extension is for addressing this issue.

vkGetPhysicalDeviceRefreshableObjectTypesKHR provides objects that have such implicit memory allocations.

Such memory can be explicitly refreshed via vkCmdRefreshObjectsKHR

This copies data from an SEU-safe memory.

The background features a complex, abstract pattern of glowing green lines and shapes against a solid black field. The lines vary in thickness and orientation, some appearing as straight streaks while others form more intricate, overlapping loops and curves. The overall effect is one of dynamic energy and technological sophistication.

# Vulkan SC Workflow

# Workflow

- Several components involved with developing Vulkan SC application.
- Vulkan SC needs a simple way to generate offline JSON pipeline.
- The main components involved in developing the Vulkan SC application are:
  - Vulkan application
  - JSON generation Layer
  - Pipeline Cache Compiler

# Workflow

## Vulkan application

To develop a Vulkan SC application, start off with a Vulkan application with the same features.

Recommendation is to have both Vulkan and Vulkan SC code co-exist, with the Vulkan SC code compiled out.

This is needed for generating the offline JSON and SPIR-V files.



# Workflow

## JSON Generation Layer

This is a standard Vulkan layer that can be used to generate the offline pipeline JSON and SPIR-V files.

Set additional environment variables as required by this layer.

Run the Vulkan application in the previous slide with this layer enabled, to obtain the JSON and SPIR-V files.

Obtain the offline JSON and SPIR-V files.

# Workflow

PCC

The obtained JSON and SPIR-V files are fed into the PCC to obtain the final pipeline cache.

This pipeline cache is finally used by the Vulkan SC application.

The layer also provides values for `VkDeviceObjectReservationCreateInfo` that need to be set by the Vulkan SC application.

# Workflow

JSON/SPV needs to be created offline and the cache needs to be obtained.

Pipeline JSON can be obtained in any way. Recommended way is to use the JSON\_generator layer.

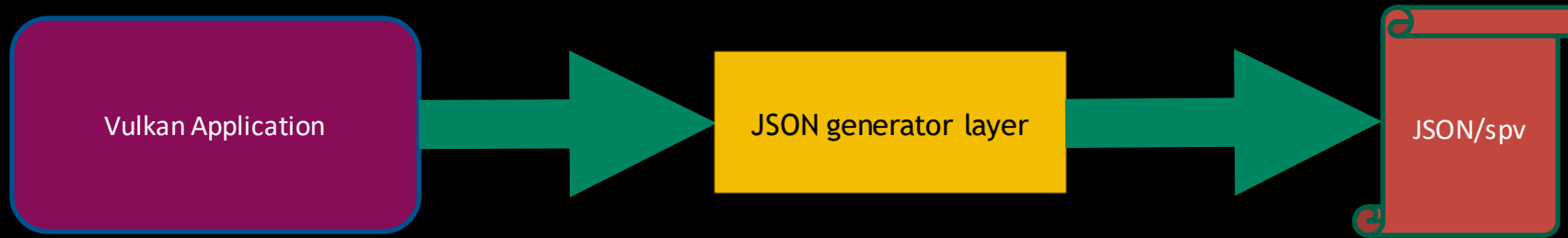
Start with Vulkan app, obtain offline json/spv.

Compile the cache and feed to VKSC.

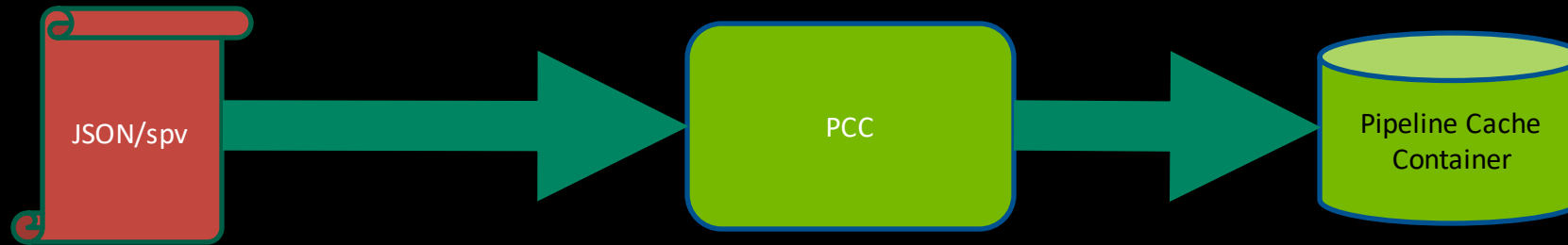
Might need to store different set of caches for different target architectures.

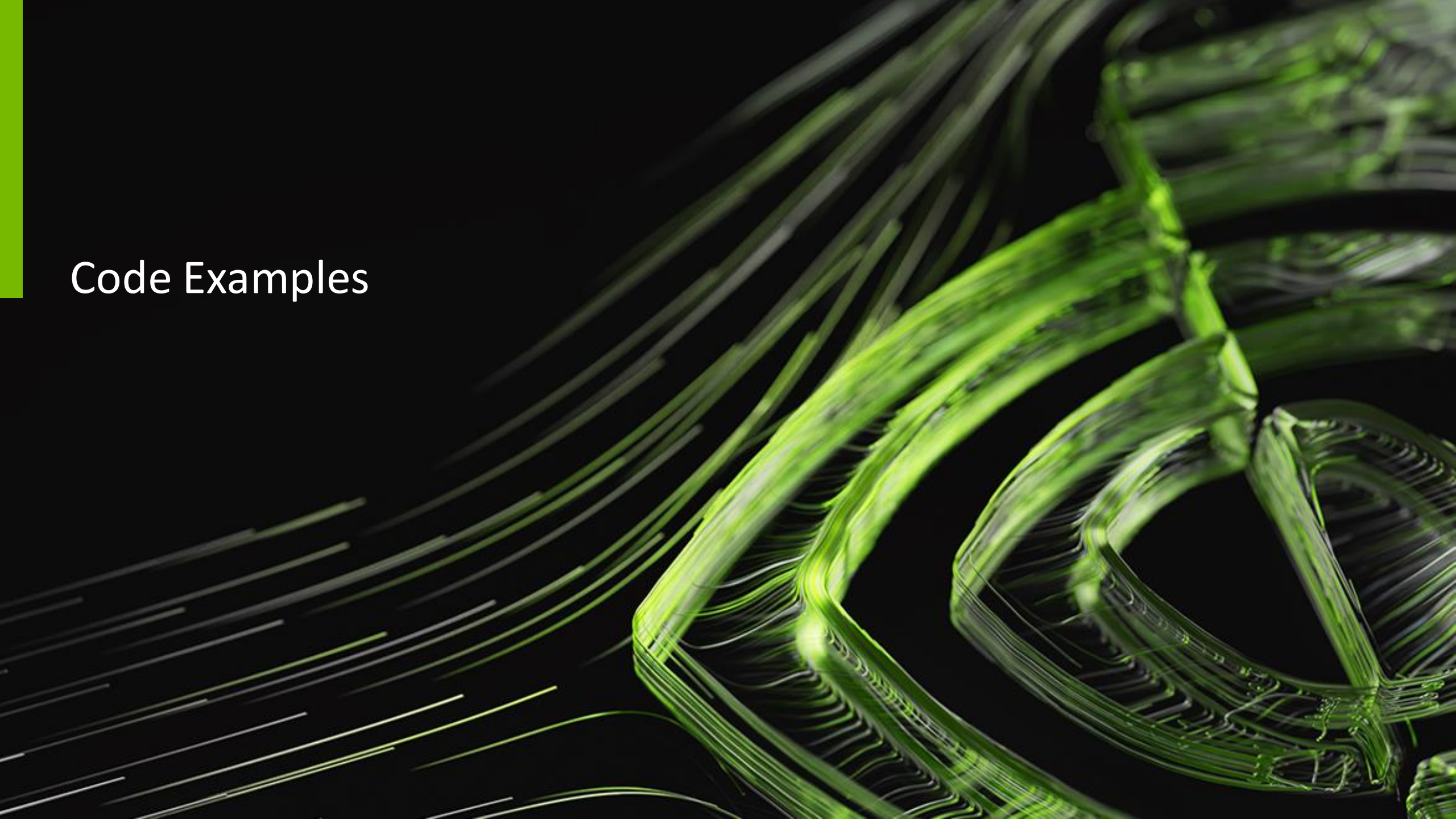
# Workflow

## 1. Generate JSON file during development



## 2. Generate pipeline cache container



The background features a black field filled with numerous thin, bright green lines that appear to be moving or vibrating, creating a sense of dynamic energy. On the left side, there is a solid, vertical green rectangular bar. The text 'Code Examples' is positioned to the right of this bar.

## Code Examples

# References

- Vulkan SC home page: <https://www.khronos.org/vulkansc/>
- Intro blog: <https://www.khronos.org/blog/vulkan-sc-overview>
- Spec: <https://registry.khronos.org/VulkanSC/specs/1.0-extensions/html/vkspec.htm>
- Vulkan SC PCUtil: <https://github.com/KhronosGroup/VulkanSC-pcutil>
- Vulkan SC Loader: <https://github.com/KhronosGroup/VulkanSC-Loader>
- Vulkan SC Validation layers: <https://github.com/KhronosGroup/VulkanSC-ValidationLayers>
- Vulkan Samples: <https://github.com/SaschaWillems/Vulkan>



